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the stroke check in the positive direction along the N axis.

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(3) For M-900+A/200P Robot, wrist load + J3 arm load cannot exceed 200kg. (4) When the reach is between 3136mm and 3350, CG of the workpiece should be within 30 degrees from the wrist downward direction.

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screwdriver and lower the spindle using this valve by turning the manual override slot below the electrical coil hood connection (DIN plug). The cable going into the connector should be labeled O1583, turn this to the 1 position to lower the spindle into the tool change position, then turn the 1/0 manual override back to 0.

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